

# TRIGONOMETRIC IDENTITIES

## Reciprocal Identities

$$\sin \theta = \frac{1}{\csc \theta} \quad \csc \theta = \frac{1}{\sin \theta}$$

$$\cos \theta = \frac{1}{\sec \theta} \quad \sec \theta = \frac{1}{\cos \theta}$$

$$\tan \theta = \frac{1}{\cot \theta} \quad \cot \theta = \frac{1}{\tan \theta}$$

## Quotient Identities

$$\frac{\sin \theta}{\cos \theta} = \tan \theta \quad \frac{\cos \theta}{\sin \theta} = \cot \theta$$

## Pythagorean Identities

$$\sin^2 \theta + \cos^2 \theta = 1$$

$$\tan^2 \theta + 1 = \sec^2 \theta$$

$$1 + \cot^2 \theta = \csc^2 \theta$$

## Cofunction Identities

$$\sin \theta = \cos (90^\circ - \theta) \quad \cos \theta = \sin (90^\circ - \theta)$$

$$\tan \theta = \cot (90^\circ - \theta) \quad \cot \theta = \tan (90^\circ - \theta)$$

$$\sec \theta = \csc (90^\circ - \theta) \quad \csc \theta = \sec (90^\circ - \theta)$$

## Sum and Difference Identities

$$\sin (\alpha \pm \beta) = \sin \alpha \cos \beta \pm \cos \alpha \sin \beta$$

$$\cos (\alpha \pm \beta) = \cos \alpha \cos \beta \mp \sin \alpha \sin \beta$$

$$\tan (\alpha \pm \beta) = \frac{\tan \alpha \pm \tan \beta}{1 \mp \tan \alpha \tan \beta}$$

## Opposite-Angle Identities

$$\sin (-A) = -\sin A \quad \cos (-A) = \cos A$$

## Double-Angle Identities

$$\sin 2\theta = 2 \sin \theta \cos \theta$$

$$\cos 2\theta = \cos^2 \theta - \sin^2 \theta$$

$$= 2 \cos^2 \theta - 1$$

$$= 1 - 2 \sin^2 \theta$$

$$\tan 2\theta = \frac{2 \tan \theta}{1 - \tan^2 \theta}$$

## Half-Angle Identities

$$\sin \frac{\alpha}{2} = \pm \sqrt{\frac{1 - \cos \alpha}{2}}$$

$$\cos \frac{\alpha}{2} = \pm \sqrt{\frac{1 + \cos \alpha}{2}}$$

$$\tan \frac{\alpha}{2} = \pm \sqrt{\frac{1 - \cos \alpha}{1 + \cos \alpha}}, \cos \alpha \neq -1$$

## Symmetry Identities

The following trigonometric identities hold for any integer  $k$  and all values of  $A$ .

$$\text{Case 1: } \sin (A + 360k^\circ) = \sin A \\ \cos (A + 360k^\circ) = \cos A$$

$$\text{Case 2: } \sin (A + 180^\circ(2k - 1)) = -\sin A \\ \cos (A + 180^\circ(2k - 1)) = -\cos A$$

$$\text{Case 3: } \sin (360k^\circ - A) = -\sin A \\ \cos (360k^\circ - A) = \cos A$$

$$\text{Case 4: } \sin (180^\circ(2k - 1) - A) = \sin A \\ \cos (180^\circ(2k - 1) - A) = -\cos A$$

# FORMULAS

## CHAPTER 1 (pp. 4–65)

Slope  $m = \frac{y_1 - y_2}{x_1 - x_2}$

## CHAPTER 2 (pp. 66–125)

### Determinant

$$\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix} = a_1 b_2 - a_2 b_1$$

$$\begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} = a_1 \begin{vmatrix} b_2 & c_2 \\ b_3 & c_3 \end{vmatrix} -$$

$$b_1 \begin{vmatrix} a_2 & c_2 \\ a_3 & c_3 \end{vmatrix} + c_1 \begin{vmatrix} a_2 & b_2 \\ a_3 & b_3 \end{vmatrix}$$

### Inverse of a Second Order Matrix

$$A^{-1} = \frac{1}{\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}} \begin{bmatrix} b_2 & -b_1 \\ -a_2 & a_1 \end{bmatrix}$$

## CHAPTER 3 (pp. 126–203)

**Direct Variation**  $y = kx^n, n > 0$

### Inverse Variation

$$x^n y = k \text{ or } y = \frac{k}{x^n}, n > 0$$

**Joint Variation**  $y = kx^n z^n$ , where  $x \neq 0, z \neq 0$ , and  $n > 0$

## CHAPTER 4 (pp. 204–273)

### Quadratic Formula

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

## CHAPTER 5 (pp. 276–341)

### Trigonometric Ratios

$$\sin \theta = \frac{\text{side opposite}}{\text{hypotenuse}}$$

$$\cos \theta = \frac{\text{side adjacent}}{\text{hypotenuse}}$$

$$\tan \theta = \frac{\text{side opposite}}{\text{side adjacent}}$$

### Inverse Trigonometric Ratios

$$\csc \theta = \frac{1}{\sin \theta} \text{ or } \frac{\text{hypotenuse}}{\text{side opposite}}$$

$$\sec \theta = \frac{1}{\cos \theta} \text{ or } \frac{\text{hypotenuse}}{\text{side adjacent}}$$

$$\cot \theta = \frac{1}{\tan \theta} \text{ or } \frac{\text{side adjacent}}{\text{side opposite}}$$

## Trigonometric Functions of an Angle in Standard Position

$$\sin \theta = \frac{y}{r} \quad \csc \theta = \frac{r}{y}$$

$$\cos \theta = \frac{x}{r} \quad \sec \theta = \frac{r}{x}$$

$$\tan \theta = \frac{y}{x} \quad \cot \theta = \frac{x}{y}$$

### Law of Sines

$$\frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C}$$

### Area of a Triangle

$$K = \frac{1}{2}bc \sin A$$

$$K = \frac{1}{2}c^2 \frac{\sin A \sin B}{\sin C}$$

### Law of Cosines

$$a^2 = b^2 + c^2 - 2bc \cos A$$

$$b^2 = a^2 + c^2 - 2ac \cos B$$

$$c^2 = a^2 + b^2 - 2ab \cos C$$

### Hero's Formula

$$K = \sqrt{s(s-a)(s-b)(s-c)}, \text{ where } s = \frac{1}{2}(a+b+c)$$

## CHAPTER 6 (pp. 342–419)

### Degree/Radian Conversion

$$1 \text{ radian} = \frac{180}{\pi} \text{ degrees}$$

$$1 \text{ degree} = \frac{\pi}{180} \text{ radians}$$

**Length of an Arc**  $s = r\theta$

### Area of a Circular Sector

$$A = \frac{1}{2}r^2\theta$$

**Angular Velocity**  $\omega = \frac{\theta}{t}$

**Linear Velocity**  $v = r\frac{\theta}{t}$

## CHAPTER 7 (pp. 420–483)

### Distance from a Point to a Line

$$d = \frac{Ax_1 + By_1 + C}{\pm \sqrt{A^2 + B^2}}$$

## CHAPTER 8 (pp. 484–549)

### Magnitude of $\overline{P_1P_2}$ in Two Dimensions

$$|\overline{P_1P_2}| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$

### Magnitude of $\overline{P_1P_2}$ in Three Dimensions

$$|\overline{P_1P_2}| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

### Inner Product of Vectors in a Plane

$$\vec{a} \cdot \vec{b} = a_1 b_1 + a_2 b_2$$

### Inner Product of Vectors in Space

$$\vec{a} \cdot \vec{b} = a_1 b_1 + a_2 b_2 + a_3 b_3$$

### Cross Product of Vectors in Space

$$\vec{a} \times \vec{b} = \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} \vec{i} - \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} \vec{j} + \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} \vec{k}$$

### Parametric Equations for the Path of a Projectile

$$x = t|\vec{v}| \cos \theta \text{ and}$$

$$y = t|\vec{v}| \sin \theta - \frac{1}{2}gt^2$$

## CHAPTER 9 (pp. 552–613)

### Distance Formula in Polar Plane

$$P_1P_2 = \sqrt{r_1^2 + r_2^2 - 2r_1r_2 \cos(\theta_2 - \theta_1)}$$

### Conversion from Polar Coordinates to Rectangular Coordinates

$$x = r \cos \theta, y = r \sin \theta$$

### Conversion from Rectangular Coordinates to Polar Coordinates

$$r = \sqrt{x^2 + y^2}$$

$$\theta = \text{Arctan} \frac{y}{x}, \text{ when } x > 0$$

$$\theta = \text{Arctan} \frac{y}{x} + \pi, \text{ when } x < 0$$

### Absolute Value of a Complex Number

$$|a + bi| = \sqrt{a^2 + b^2}$$

### Polar Form of a Complex Number

$$r(\cos \theta + i \sin \theta)$$

### Product of Complex Numbers in Polar Form

$$r_1(\cos \theta_1 + i \sin \theta_1) \cdot$$

$$r_2(\cos \theta_2 + i \sin \theta_2) =$$

$$r_1 r_2 [\cos(\theta_1 + \theta_2) + i \sin(\theta_1 + \theta_2)]$$

(continued)

# FORMULAS

## Quotient of Complex Numbers in Polar Form

$$\frac{r_1(\cos \theta_1 + i \sin \theta_1)}{r_2(\cos \theta_2 + i \sin \theta_2)} = \frac{r_1}{r_2}[\cos(\theta_1 - \theta_2) + i \sin(\theta_1 - \theta_2)]$$

## De Moivre's Theorem

$$[r(\cos \theta + i \sin \theta)]^n = r^n(\cos n\theta + i \sin n\theta)$$

## CHAPTER 10 (pp. 614–693) Distance Formula for Two Points

$$d = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$

## Midpoint of a Line Segment

$$\left(\frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2}\right)$$

## Rotation Equations

$$x = x' \cos \theta + y' \sin \theta$$

$$y = -x' \sin \theta + y' \cos \theta$$

## Angle of Rotation

$$\theta = \frac{\pi}{4}, \text{ if } A = C \text{ or } \tan 2\theta = \frac{B}{A - C}, \text{ if } A \neq C$$

## CHAPTER 11 (pp. 694–755)

### Exponential Growth or Decay Formulas

$$N = N_0(1 + r)^t \quad N = N_0 e^{kt}$$

### Compound Interest Formula

$$A = P\left(1 + \frac{r}{n}\right)^{nt}$$

### Continuously Compounded Interest Formula

$$A = Pe^{rt}$$

### Change of Base Formula

$$\log_a n = \frac{\log_b n}{\log_b a}$$

$$\text{Doubling Time } t = \frac{\ln 2}{k}$$

## CHAPTER 12 (pp. 758–835)

### $n$ th Term of an Arithmetic Sequence

$$a_n = a_1 + (n - 1)d$$

### Sum of an Arithmetic Sequence

$$S_n = \frac{n}{2}(a_1 + a_n)$$

### $n$ th Term of a Geometric Sequence

$$a_n = a_1 r^{n-1}$$

## Sum of a Finite Geometric Sequence

$$S_n = \frac{a_1 - a_1 r^n}{1 - r}$$

## Sum of an Infinite Geometric Series

$$S_n = \frac{a_1}{1 - r}$$

## Euler's Formula

$$e^{i\alpha} = \cos \alpha + i \sin \alpha$$

## CHAPTER 13 (pp. 836–887)

### Definitions of Permutations

$$P(n, n) = n! \quad P(n, r) = \frac{n!}{(n - r)!}$$

### Definition of Combination

$$C(n, r) = \frac{n!}{(n - r)! r!}$$

### Permutation of $n$ objects with repetitions ( $p$ alike and $q$ alike)

$$\frac{n!}{p! q!}$$

### Circular Permutations of $n$ Objects

$$\frac{n!}{n} \text{ or } (n - 1)!$$

### Probability of Two Independent Events

$$P(A \text{ and } B) = P(A) \cdot P(B)$$

### Probability of Two Dependent Events

$$P(A \text{ and } B) = P(A) \cdot P(B \text{ following } A)$$

### Probability of Mutually Exclusive Events

$$P(A \text{ or } B) = P(A) + P(B)$$

### Probability of Inclusive Events

$$P(A \text{ or } B) = P(A) + P(B) - P(A \text{ and } B)$$

### Conditional Probability

$$P(A | B) = \frac{P(A \text{ and } B)}{P(B)} \text{ where } P(B) \neq 0$$

## CHAPTER 14 (pp. 888–939)

$$\text{Arithmetic Mean } \bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$$

### Mean of the Data in Frequency Distribution

$$\bar{X} = \frac{\sum_{i=1}^k (f_i \cdot X_i)}{\sum_{i=1}^k f_i}$$

## Semi-Interquartile Range

$$Q_R = \frac{Q_3 - Q_1}{2}$$

## Mean Deviation

$$MD = \frac{1}{n} \sum_{i=1}^n |X_i - \bar{X}|$$

## Standard Deviation

$$\sigma = \sqrt{\frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2}$$

## Standard Deviation of the Data in a Frequency Distribution

$$\sigma = \sqrt{\frac{\sum_{i=1}^n (X_i - \bar{X})^2 \cdot f_i}{\sum_{i=1}^n f_i}}$$

## Standard Error of the Mean

$$\sigma_{\bar{X}} = \frac{\sigma}{\sqrt{N}}$$

## CHAPTER 15 (pp. 941–983)

### Constant Multiple of a Power Rule for Derivatives

If  $f(x) = cx^n$ , where  $c$  is a constant and  $n$  is a rational number, then  $f'(x) = cnx^{n-1}$ .

### Constant Multiple of a Power Rule for Antiderivatives

If  $f(x) = kx^n$ , where  $n$  is a rational number other than  $-1$  and  $k$  is a constant, the antiderivative is  $F(x) = k \cdot \frac{1}{n+1} x^{n+1} + C$ .

### Definite Integral

$$\int_a^b f(x) dx = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i) \Delta x \text{ where}$$

$$\Delta x = \frac{b - a}{n}$$

### Fundamental Theorem of Calculus

$\int_a^b f(x) dx = F(b) - F(a)$ , where  $F(x)$  is the antiderivative of  $f(x)$ .

# SYMBOLS

$=$	is equal to	$\sin^2 \theta$	$(\sin \theta)^2$	$M_d$	median
$\neq$	is not equal to	$\infty$	infinity	$\sigma_{\bar{X}}$	standard error of the mean
$<$	is less than	$i$	$\sqrt{-1}$	$MD$	mean deviation
$\leq$	is less than or equal to	$r \text{ cis } \theta$	$r(\cos \theta + i \sin \theta)$	$f(x)$	$f$ of $x$ or the value of function $f$ at $x$
$\nlessdot$	is not less than	$\vec{v}$ or $\overline{AB}$	a vector or directed line segment	$f'(x)$	$f$ prime of $x$ or the derivative of $f(x)$
$>$	is greater than	$(x, y)$	vector with initial point at origin and terminal point at $(x, y)$	$\frac{dy}{dx}$	derivative of $y$
$\geq$	is greater than or equal to	$ \vec{v} $	magnitude of the vector $\vec{v}$	$f \circ g$ or $f(g(x))$	composite of functions $f$ and $g$
$\nlessdot$	is not greater than	$\vec{a} \cdot \vec{b}$	inner product of vectors $\mathbf{a}$ and $\mathbf{b}$	$\int f(x) dx$	indefinite integral
$\approx$	is approximately equal to	$\vec{a} \times \vec{b}$	cross product of vectors $\mathbf{a}$ and $\mathbf{b}$	$\int_a^b f(x) dx$	definite integral
{ }	set notation	$e$	base of natural logarithms; $\approx 2.718$	$\alpha$	alpha
$\pm$	plus or minus	$n!$	$n$ factorial	$\beta$	beta
$\mp$	minus or plus	$\ln x$	logarithm of $x$ with base $e$ ; natural logarithm	$\gamma$	gamma
$\triangle ABC$	triangle $ABC$	$\log_a x$	logarithm of $x$ with base $a$	$\Delta$ or $\delta$	delta
$RTS$	arc $RTS$	$\log x$	logarithm of $x$ with base 10; common logarithm	$\epsilon$	epsilon
$\angle ABC$	angle $ABC$	$\lim_{x \rightarrow a}$	the limit as $x$ approaches $a$	$\theta$	theta
$m\angle ABC$	measure of angle $ABC$	$P(n, r)$	number of permutations of $n$ objects, taken $r$ at a time	$\lambda$	lambda
$AB$	measure of line segment $AB$	$C(n, r)$	number of combinations of $n$ objects, taken $r$ at a time	$\mu$	mu
$\overline{AB}$	line segment $AB$	$\bar{X}$	$\bar{X}$ bar or arithmetic mean	$\pi$	pi
$ x $	the absolute value of $x$			$\sigma$	sigma; standard deviation
$x^n$	the $n$ th power of $x$			$\sum$	sigma; summation symbol
$\sqrt{x}$	the square root of $x$			$\phi$	phi
$\sqrt[n]{x}$ or $x^{1/n}$	the $n$ th root of $x$			$\omega$	omega; angular velocity
$\lceil x \rceil$	greatest integer not greater than $x$				
$A^{-1}$	inverse of matrix $A$				
$a_{ij}$	the element of the $i$ th row and the $j$ th column of matrix $A$				
$\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}$	the determinant $a_1b_2 - a_2b_1$				
$\sin^{-1} x$	arcsin $x$				